$$\frac{\S 1. \text{ Non-Abelian Gauge Theories}}{\S 1.1 \text{ Gauge invariance}}$$

$$\begin{array}{l} \$ 1.1 \text{ Gauge invariance} \\
& & & & & \\ & & & \\ & & & \\ & & & \\ & &$$

The last equality flows from the
"jacobi-identity"
$$O = [[t_{a,1}t_{b}], t_{r}] + [[t_{r}, t_{a}], t_{b}] + [[t_{b}, t_{r}], t_{a}]$$

 $\Rightarrow adjoint representation: $(t_{a}^{A})^{b}_{r} = -iC^{b}ra$
 $E \xrightarrow{\text{xample}:}$
i) "iso-spin":
 $Y = \begin{pmatrix} Y_{p} \\ t_{n} \end{pmatrix}$ with t_{a} given by
 $t_{1} = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad t_{1} = \frac{1}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad t_{3} = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -i \end{pmatrix}$
satisfying the commutation relations (a) with
 $C^{b} dy_{5} = \sum r_{A,5}$
ii) adjoint representation:
 $t_{1}^{A} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & -i \\ 0 & 1 & 0 \end{bmatrix}, \quad t_{2}^{A} = \begin{bmatrix} 0 & 0 & i \\ 0 & 0 & 0 \\ -i & 0 & 0 \end{bmatrix}$
Differentiating equation (i) gives
 $S(2n, Y_{E}(x)) = iE^{c}(x)(t_{x})_{e} \quad (2, Y_{m}(x)) + i(2n E^{b}(x))(t_{a})_{e} \quad T_{m}(x)$
 $\Rightarrow to make the keyrangian invariant, we need
a field A^{a}_{m} with:
 $8A^{b}_{m} = 2\pi E^{b} + iE^{b}(t_{a}^{A})^{b}_{r} A^{b}_{m}$ (3)$$

$$\rightarrow (D_{n} \forall k)_{\ell} = \partial_{n} \forall_{\ell} (x) - i A_{n}^{S} (x) (t_{s})_{\ell} \overset{m}{\psi}_{m} (x)$$
and thus
$$S(D_{n} \forall)_{\ell} = i \varepsilon^{k} (t_{s})_{s} \overset{m}{\to} \psi_{m} - i C_{\gamma s} \varepsilon^{k} A_{n}^{\gamma} (t_{s})_{\ell} \overset{m}{\psi}_{m}$$

$$+ A_{n}^{\gamma} (t_{s})_{\ell} \overset{m}{\to} \psi_{m} \varepsilon^{k}$$
Using (1), we get
$$S(D_{n} \forall)_{\ell} = i \varepsilon^{k} (t_{s})_{s} \overset{m}{(D_{n} \psi)_{m}}$$
We also notice
$$([D_{v}, D_{n}] \psi)_{\ell} = -i (t_{r})_{\ell} \overset{m}{\to} \overset{r}{V}_{m} \psi_{m},$$
where
$$F^{\gamma} v_{n} = \partial_{v} A_{n}^{\gamma} - \partial_{n} A_{v}^{\beta} v + C_{s}^{\gamma} A_{v}^{k} A_{n}^{S}$$

$$S F_{vm}^{\beta} = i \varepsilon^{k} (t_{s}^{k})_{s}^{\beta} F^{r} v_{m} = \varepsilon^{k} C_{\gamma k} F^{r} v_{m} (x)$$
finite transformations:
$$\psi_{\ell} (x) \rightarrow \psi_{\ell A} (x) = [\exp(i t_{s} \Lambda^{k} (x))]_{s} \overset{m}{\psi} \psi_{m} (x) \qquad (4)$$
want
$$(\partial_{n} - i t_{m} A_{m}^{k}) \psi_{A} = \exp(i t_{s} \Lambda^{k}) (\partial_{n} - i t_{s} A_{m}^{k}) \psi_{A}$$

$$+ A_{mA}^{k} = \exp(i t_{s} \Lambda^{k}) = \exp(-i t_{s} \Lambda^{k})$$

$$\frac{\S{1.2} \quad Gauge theory \quad Kagrangians \quad and \\ \underline{simple \quad Xie \quad Groups} \\ Our \quad Kagrangian \\ \chi = \chi(Y, D_n Y, D_r D_n Y, \dots, F_{nr}^x, D_r F_{nr}^x, \dots) \\ must \quad be \quad gauge invariant : \\ \frac{\Im Z}{\Im Y_e} : (Y_n)_e \quad Y_m + \frac{\Im \chi}{\Im D_n Y_e} : (Y_n)_e \quad (D_n Y)_m \\ + \quad \frac{\Im Z}{\Im D_r D_n Y_e} : (Y_n)_e \quad (D_r D_n Y)_m + \dots + \frac{\Im \chi}{\Im F_n} C_{rx}^s F_{rr}^r \\ + \quad \frac{\Im Z}{\Im D_r F_{nr}} \quad C_{rx}^s D_r F_{nr}^r + \dots = 0 \qquad (1) \\ \longrightarrow \text{ does not depend an gauge field } A_n^x explicitly, \\ anly implicitly through F_{nr} and D_n \\ (e.e. no terms - I_m X_r An A_r) \\ \chi_A = -\frac{1}{4} \Im_{AS} F_{nr}^x F_{rrr}^s F_{rrr} F_{rrr} \\ C_{orstant}^s F_{nrr}^s F_{rrr}^s F_{rrr} f_{rrr} \\ S_n = \frac{1}{2} \Theta_{AS} F_{rrr}^x F_{rrr}^s F_{rrr}^s (breaks parity) \\ C_{orstant} f metrix \\ (= d(A_r F) \rightarrow devirative, does not affect Feynman robes) \end{cases}$$